



Remote Sensing of Marine Litter Workshop 2023 16-17 October 2023 els.knaeps@vito.be



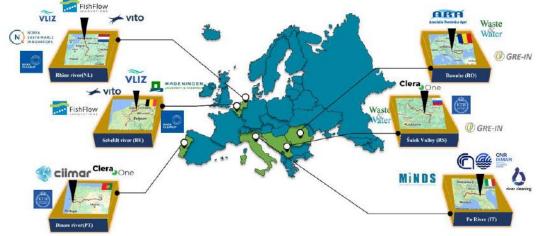
INSPIRE



INSPIRE will contribute to the drastic reduction of litter, macro and microplastics in European rivers

The solution of INSPIRE is a holistic approach conceptualized in the "DCP concept":

- **DETECTION** of the pollution present in the river and at the riverbank;
- <u>COLLECTION</u> of litter and macroplastics at the riverbank; and litter, macro- and microplastics in the river;
- **PREVENTION** of litter, macro and microplastics to enter the river by:
 - Collecting it from its waste stream before it can enter the river
 - Developing biodegradable alternatives for non-degradable polluting products



















Met je eigen drone aan de slag

Geweldig dat je een vlucht wil uitvoeren voor Waste Watchers! Om je vlucht correct en vlot te laten verlopen, neem je deze richtlijnen best grondig door.

Wettelijk in orde

- Als je een drone met een camera aanschaft moet je je bij de FOD Mobiliteit registreren als exploitant, ook als hobbyist. Dat kan gratis op het online dronesPortal FOD Mobiliteit en Vervoer. Je krijgt dan een exploitatienummer dat je zichtbaar moet aanbrengen op je drone(s).
- Bij je registratie geef je een polisnummer op die burgerlijke aansprakelijkheid voor je drone activiteiten dekt. Is het enkel voor je hobby, dan volstaat meestal je familiale polis.
- Om te vliegen met een drone van minder dan 250 g volstaat het in principe om de handleiding te lezen. Een opleiding is niet verplicht, maar het theoretisch Open A1 certificaat halen, kan eenvoudig, gratis en online.
- Het is jouw verantwoordelijkheid als piloot om een veilige en legale dronevlucht uit te voeren. Het Waste Watchers project voorziet op geen enkele manier in ontheffingen voor de geldende regels en beperkingen.

Welke drone?

Voor Waste Watchers kan je gebruikmaken van een DJI Mavic Mini, Mini 2, Mini 2 SE, Mini 3 en Mini 3 Pro. Heb je een Parrot ANAFI, DJI Mavic Air (niet de Air 2 of Air 2S), DJI Mavic 3 Classic, Mavic 3 of Mavic 3 Cine (als je voor beide laatste types een C1-label hebt aangevraagd) kun je ook aan de slag, maar vlieg dan niet recht boven de jaagpaden. Het is met deze drones niet toegestaan boven voorbijgangers te vliegen.



Technologies

Riverbank litter using drones











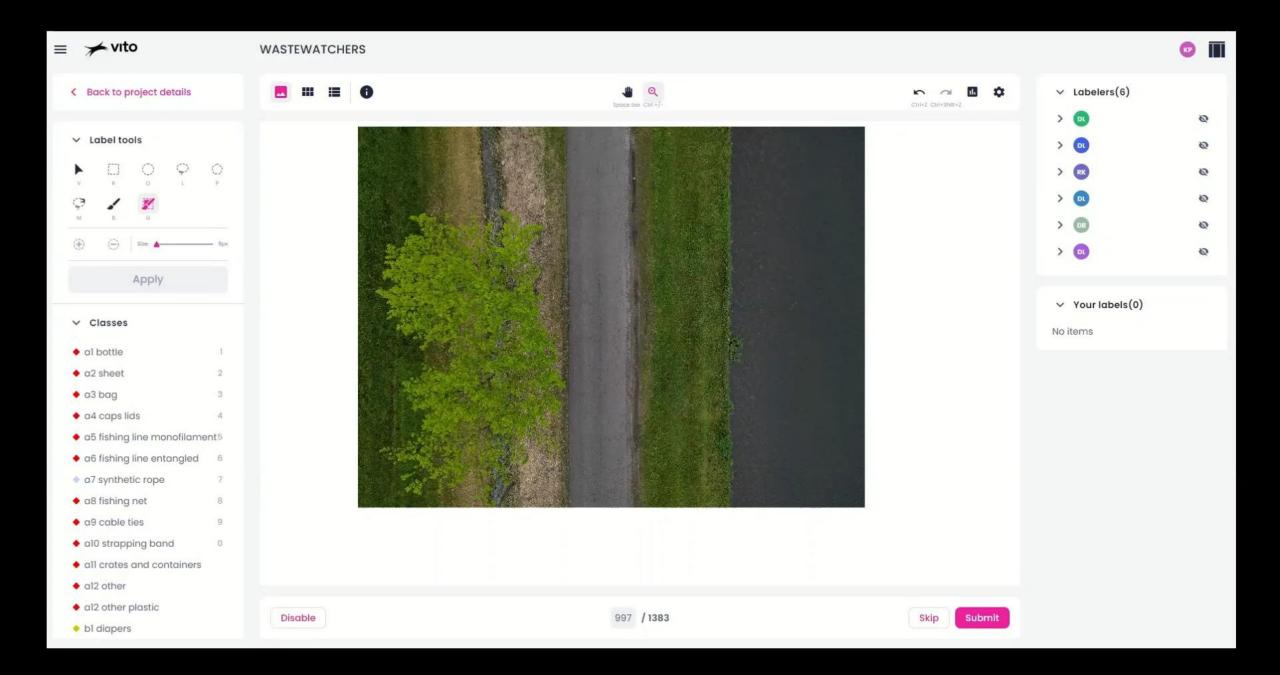
Riverbank litter - Dataset













- Different types of litter manually labelled.
- Converted to patches of 64-pixels, class of 'litter' or 'no litter'.
- Resnet-50 model trained with equal number of patches with and without litter.
 - Prediction accuracy of 91.6%
- Benefits of approach include:
 - Fast and simple to train.
 - Can easily include more labelled data.
 - End product easy to look at.

Labelled



Litter patches







No Litter Patches





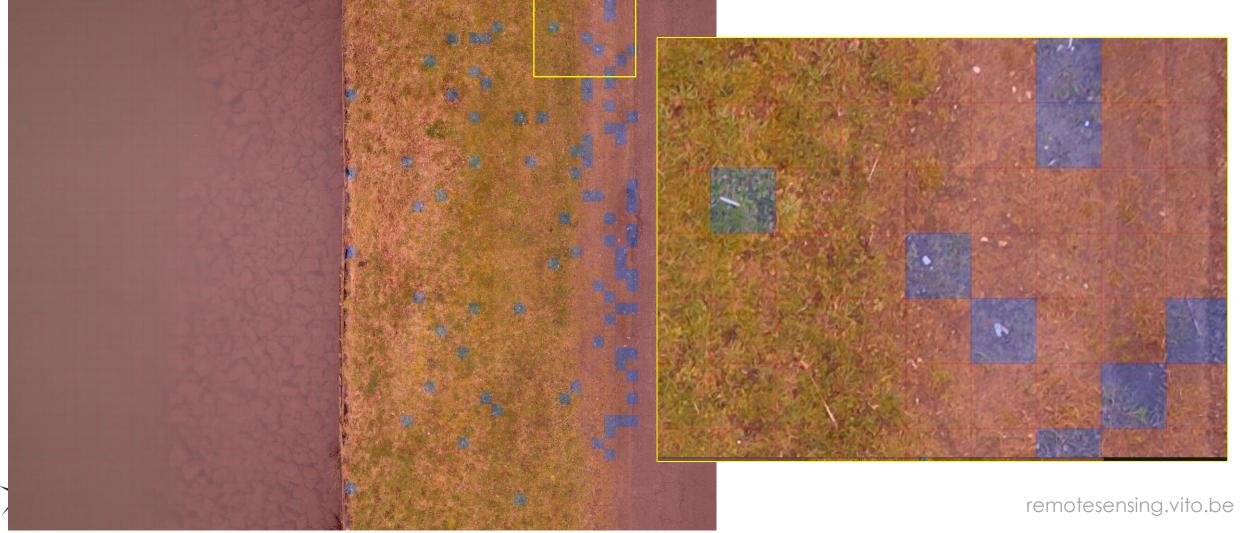


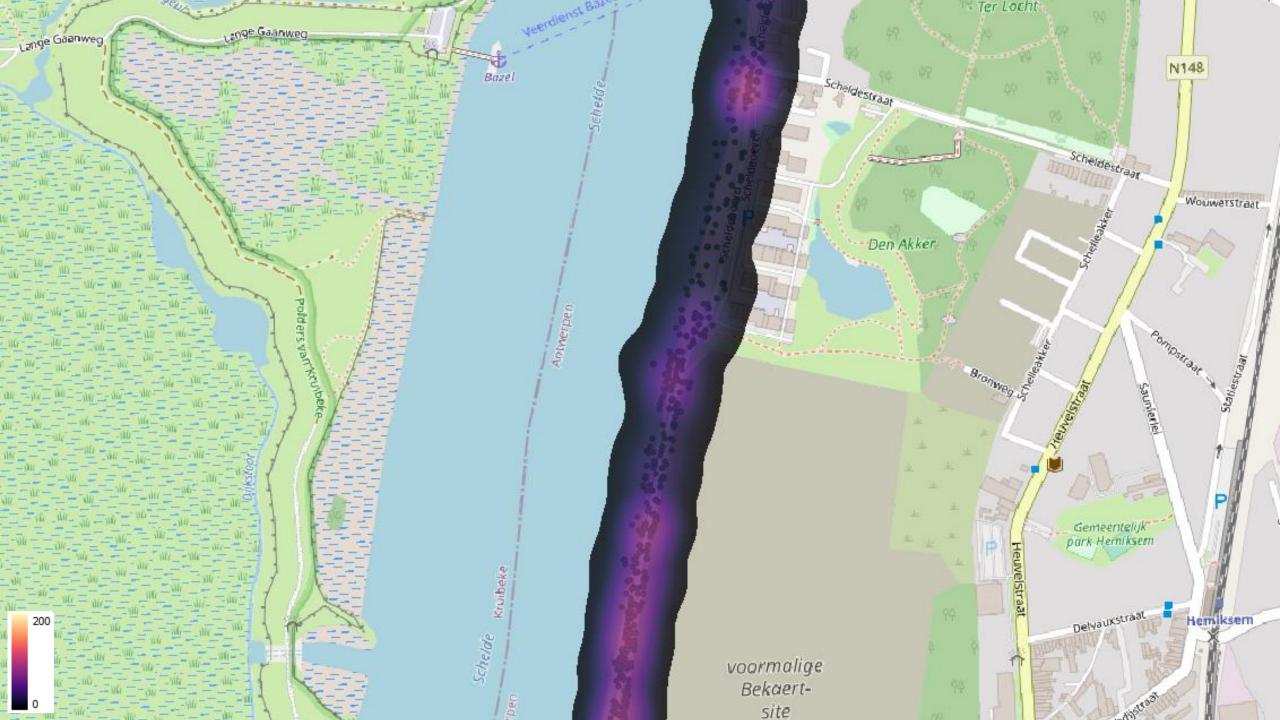




Blue = Litter detected in patch.

Red = No litter detected in patch.







Plastic flux

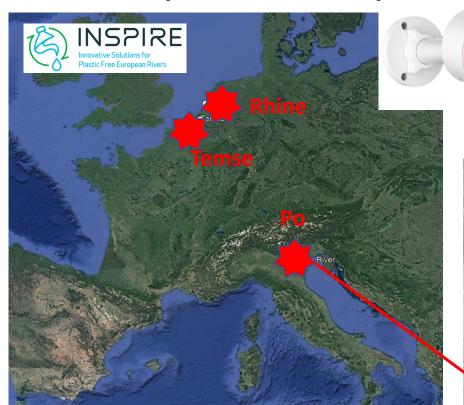
Test and develop set-up





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Operational set-up



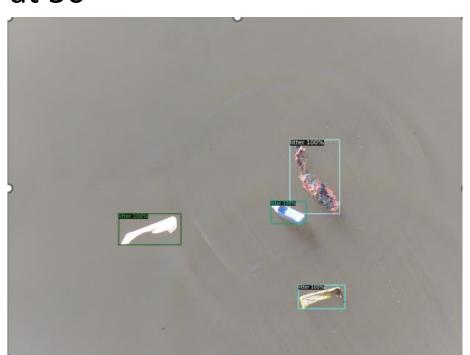
camera = RLC-1212a

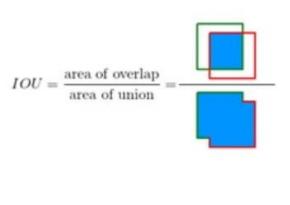




Al model for RGB data to detect floating litter

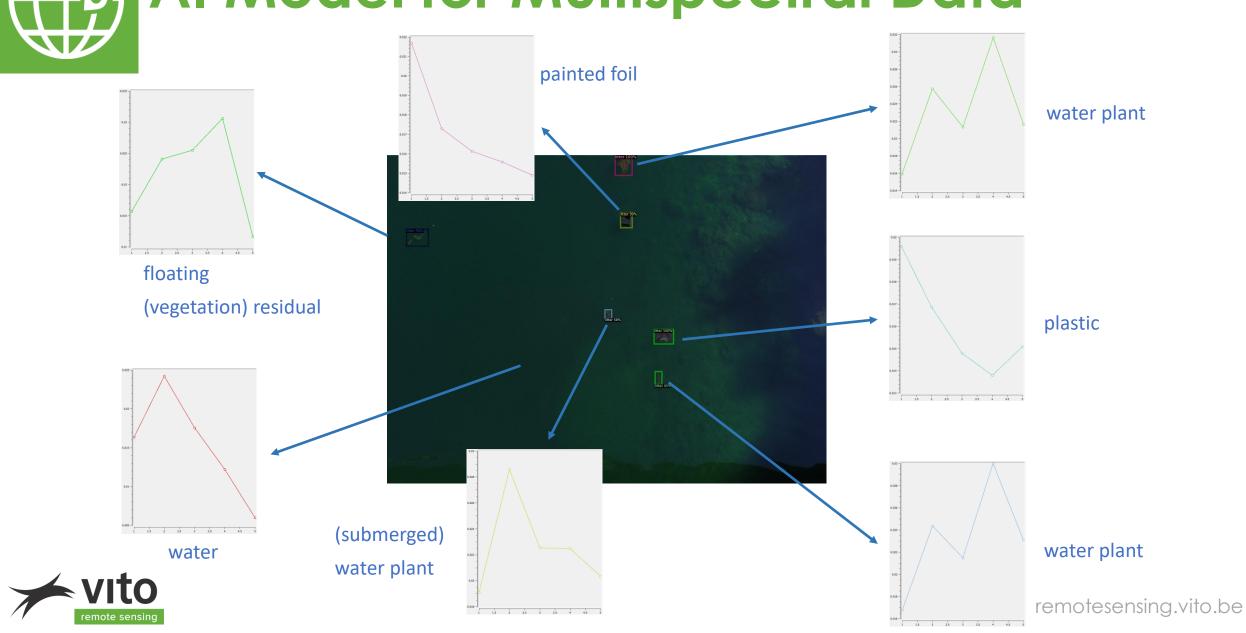
- Faster RCNN (Region-Based Convolutional Neural Network) was selected (Faster, 2015)
- average precision 50 obtained at 89.88% for IOU at 50

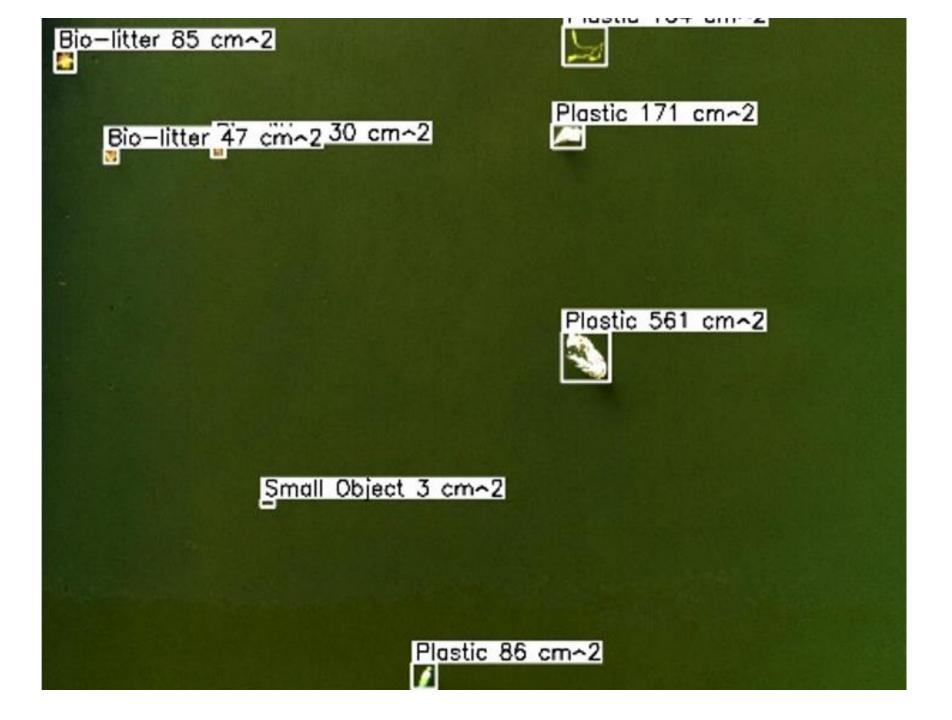






Al Model for Multispectral Data

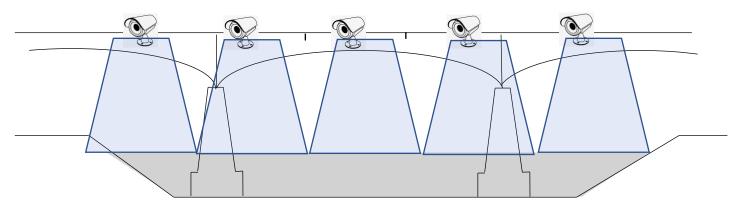




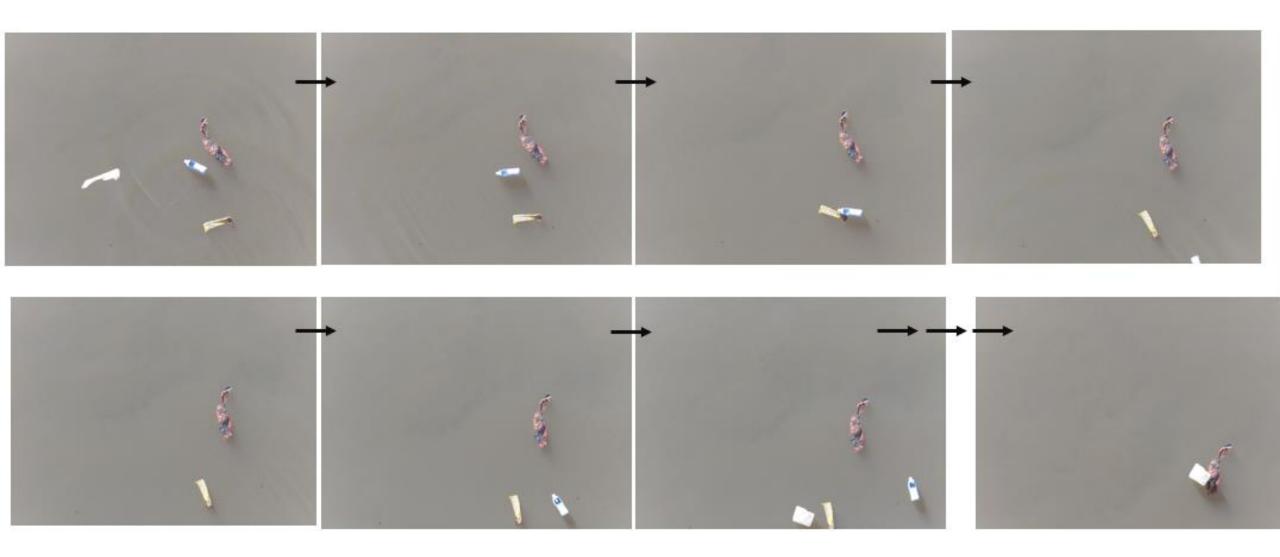


From detecting objects to plastic flux

- How much objects per unit of time
- Cover complete cross section of the river: add more cameras, extrapolation...
- We need unique counts but doubles due to frame rate, tide, wind...





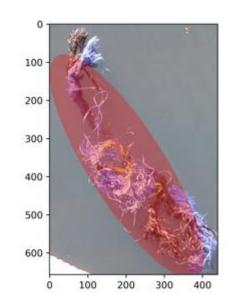


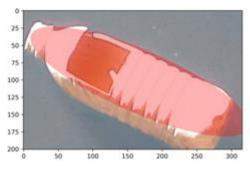


Add intelligence

Use:

- From bounding box to shape
- Colour: via transformation (RGB => HSV or LAB)
- Eccentricity of ellipse
- Solidity (#pixels_{region} / #pixels_{convex hull})
- Area
- Perimeter
- Axes of ellipse
- Example: rope vs bottle
 - solidity_{rope} << solidity_{bottle}
 - perimeter_{rope} >> perimeter_{bottle}







Comparison score

| ImageDire | ImageName | LitterIdInI | EpochTimeAcq | HueSaturation_x | HueSaturation_y | Eccentricity | Solidity | Area | Perimeter | AxisMajorLength | AxisMinorLength | LitterIdUnique | Comparisor |
|--------------|--------------|-------------|--------------|------------------|-----------------|--------------|-----------|-------|-----------|-----------------|-----------------|----------------|------------|
| 0 P:\code\pl | 20220308T132 | idii_0 | 1646742004 | 0.0 | 0.0 | 0.9827353566 | 0.6953381 | 39377 | 1665 | 611 | 113 | id_00000001 | -1 |
| 0 P:\code\pl | 20220308T132 | idii_1 | 1646742004 | 0.07330386971029 | 0.0803807775028 | 0.9531148787 | 0.6080410 | 19101 | 2292 | 355 | 107 | id_000000002 | -1 |
| 0 P:\code\pl | 20220308T132 | idii_2 | 1646742004 | 0.0 | 0.0 | 0.9652265632 | 0.6739971 | 16550 | 1367 | 342 | 89 | id_00000003 | -1 |
| 0 P:\code\pl | 20220308T132 | idii_3 | 1646742004 | 0.14133737556981 | 0.0024864244620 | 0.9464425372 | 0.1336085 | 13786 | 8202 | 544 | 175 | id_00000004 | -1 |
| 0 P:\code\pl | 20220308T132 | idii_0 | 1646742006 | 0.15533980582524 | 1,94E-01 | 0.9528838513 | 0.1495009 | 15234 | 8785 | 576 | 174 | id_00000004 | 3.5 |
| 0 P:\code\pl | 20220308T132 | idii_1 | 1646742006 | 0.0 | 0.0 | 0.9716386347 | 0.6629007 | 15549 | 1319 | 349 | 82 | id_000000003 | 4.5 |
| 0 P:\code\pl | 20220308T132 | idii_2 | 1646742006 | 0.08500295907978 | 0.0813346629519 | 0.9557375336 | 0.7202333 | 21486 | 1894 | 347 | 102 | id_00000005 | -1 |
| 0 P:\code\pl | 20220308T132 | idii_0 | 1646742009 | 0.15859030837004 | 0.0 | 0.9493147934 | 0.1679957 | 15969 | 9035 | 555 | 174 | id_00000004 | 4.5 |
| 0 P:\code\pl | 20220308T132 | idii_1 | 1646742009 | 0.0 | 0.0 | 0.9709794195 | 0.7380136 | 16147 | 1062 | 343 | 82 | id_000000006 | -1 |



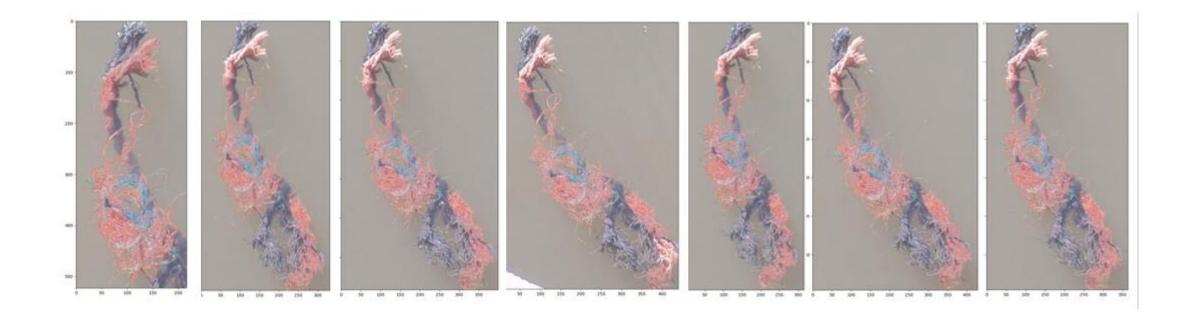


- Identifying all objects in previous images
- Calculate metrics
- Then compare in next image



Comparison score

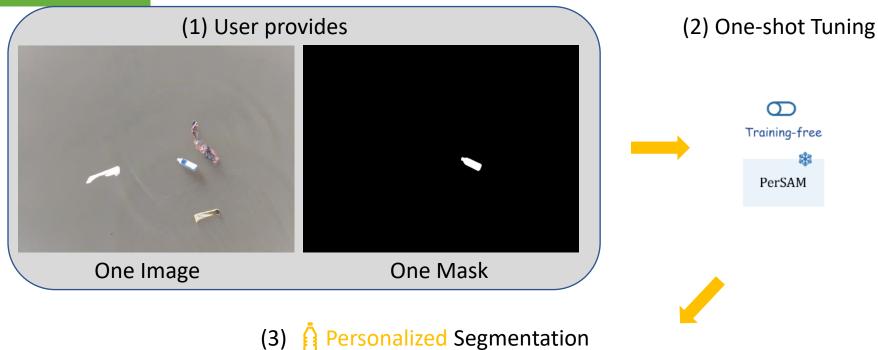
7 matches for the rope







Personalize SAM with One Shot





https://arxiv.org/pdf/2305.03048.pdf







Based on Segment Anything (Meta AI) segment-anything.com/

remotesensing.vito.be



Riverbank litter

More diverse backgrounds, more training

Plastic flux

- Long term monitoring
- Use ellipse to derive the size of the object
- Improve object detection model to better distinguish objects that are connected.
- Use multispectral data to distinguish different types of litter and application types



